Vickers®

Accessories

Power Amplifiers with PID Modules

FATON

EEA-PAM-5**-D-32 Series

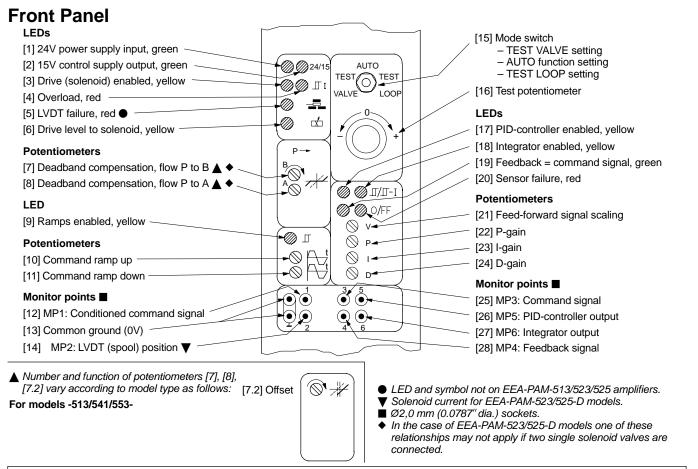
General Description

The EEA-PAM-5**-D-32 Eurocards are power amplifiers with integrated PID modules. Each of these cards replaces two conventional electronic cards.

Features and Benefits

- Includes all features of "A" amplifiers (except gain)
- User configurable PID feed-forward, closed-loop operation

- Command input ramps
- Analog feedback sensor interface
- Automatic switch-over p/Q function
- Built-in test feature
- The design reduces the amount of external wiring, saves space in the rack enclosure and requires only one 24V supply
- The general purpose, integrated module can be configured using DIL switches (D1-D9) and potentiometers for the following applications:
- Closed-loop pressure control using either proportional pressure valves or servo-performance proportional valves
- Closed-loop velocity control
- Closed-loop position control
- p/Q control with internal or external switch-over from Q to p
- The DIL- switch and potentiometer settings can easily be reconfigured on different cards





January 1996 GB-2474

Model Codes

Amplifier model	For valves			
EEA-PAM-513-D-32	KCG-3, KCG-6/8			
	KX(C)G-6/8			
EEA-PAM-523-D-32	K*G4V-3, KDG5V-5/7/8			
EEA-PAM-525-D-32	K*G4V-5			
EEA-PAM-533-D-32	KF*G4V-3			
EEA-PAM-535-D-32	KF*G4V-5			
EEA-PAM-541-D-32	KHDG5V-5/7/8 with zerolapped mainspool			
EEA-PAM-553-D-32	KSDG4V-3			
EEA-PAM-561-D-32	KFDG5V-5/7			
EEA-PAM-568-D-32	KFDG5V-8			
EEA-PAM-571-D-32	CVU-**-EFP1			
EEA-PAM-581-D-32	KHDG5V-5/7/8			

Operating Data

Power (input) supply		See appropriate base amplifier, e.g. for EEA-PAM-535-D-32 see EEA-PAM-535-A-32
Control (output) supplies	z22	+15V for LVDTs only
Reference voltages	z2	+10V x 5 mA
	b2	-10V x 5 mA
Analog inputs:		
Command inputs		
Direct-voltage inputs	b6, b8, b10, z8	
Inverting-voltage input	z10	
Voltage range		±10V
Input impedance (voltage)		47 kΩ
Current input	z6	
Current range		±20 mA
Input impedance (current)		100Ω
Feed-forward input	d8	
Input impedance		6 kΩ
Voltage range		±10V
Input to ramp generator	d28	
Input impedance		10 kΩ
Voltage range		±10V
Inputs from sensors		
Voltage input	d2	
Input impedance		1 ΜΩ
Voltage range		0 to 10V, or ±10V■
Current input		
Input impedance		100Ω
Current range (See "DIL Switches" five page	-	4-20 mA or 0-20 mA
Monitoring of sensor failure for sensors wit	h a current outout only	

[■] The demand signal should have the same voltage range as the sensor feedback, i.e. 0 to 10V, or \pm 10V.

Digital inpute:		
Digital inputs:	-04	
Drive enable (power available to solenoid)	z24	/
Ramps enable	b24	
Integrator enable	d14	
		Warning: In a power-up sequence, the integrator should
		not be enabled until all hydraulic, electric and control power and signals are applied and stable. Abrupt or
		unpredictable motion may occur if integrator is enabled
		during this transition time.
PID-controller enable	d12	ŭ
Enabled		17 to 40V
Disabled		0 to 3,5V
Load current		≤10 mA
Digital outputs:		
Sensor failure	d18	
Sensor failure	410	Vcc –2V
Sensor o.k.		<3V
		≤100 mA
Load current (withstands a continuous short-circuit condition)		≥ 100 IIIA
This output may be used only in conjunction with sensors		
providing a current output (4-20 mA)	-14.0	
Feedback = command signal	d10	
Feedback matches demand		Vcc –2V
Feedback does not match demand		<3V
Load current (withstands a continuous short-circuit condition)		≤ 100 mA
The load at pin d18 and pin d10 has to be connected to ground		
Analog outputs:		
PID-controller output	d4	
Error signal	d22	
Feedback signal	d24	
Load impedance		\geq 10 k Ω ; short-circuit proof
Voltage range		±10V
Output from ramp generator	d26	
Load resistance		≥5 kΩ; short-circuit proof
Voltage range		±10V
Alarm output (drive output status):	z12	
Set alarm		Enable amplifier (on pin z24) >500 ms after switching
		power on.
Signal		HIGH when alarm is activated.
oignai		Output = Supply volts minus 2 volts.
		I = 50 mA max.
		LOW when solenoid overload has occurred.
		(Maintained until reset).
		Output = 0 to +/-2 volts.
Reset after failure		Output resistance = 50 ohms.
	L 40	Disable and re-enable on pin z24.
Ramp active indicator:	b12	Outset 401/
Drive ramping up		Output >10V
Drive ramping down		Output <-10V
Drive not ramping		Output 0 ± 10V
Output resistance		10 kΩ
Drive signal zero indicator:	b20	
Drive signal at null (within deadband limits)		Output = Supply minus 1,5V; I = 50 mA max.
Drive active		Output = $0 \pm 2V$
Output resistance		50Ω
· · · · · · · · · · · · · · · · · · ·		<u> </u>

Continued on next page

Detectionators	
Potentiometers:	V 2007 to 40007
Feed-forward	V = 20% to 100%
P-gain (depends on DIL switch D2):	P = 0.1 to 50 V/V
I-gain range	$K_i = 0.5 \text{ to } 100 \text{ V/s/V}$
D-gain range	$K_d = 0$ to 0,05 V/V/s
Sensor signal gain range■	90% to 120%
Sensor signal offset range■	±10%
Monitor points:	
Conditioned command signal	MP1
LVDT (spool) position▲	MP2
Command signal	MP3
•	MP4
<u>.</u>	MP5
Integrator output (100%, independent of D3, D4, D5)	MP6
Voltage range	±10V
Monitor point impedance	10 kΩ
Ambient conditions:	
Storage temperature range	-25 to +85°C (-13 to +185°F)
Operating temperature range	0 to 50°C (32 to 122°F)
Mass	0,4 kg (0.88 lb) approx.
Installation and start-up guidelines (supplied with product)	9161
Installation wiring requirements for Vickers electronic products	2468
Application notes (available on request)	9056
Supporting products:	See catalogs:
Power supply unit options	2419
Electronic accessories	2460
Portable test equipment	2462 and 2315

[■] Located on PID module.

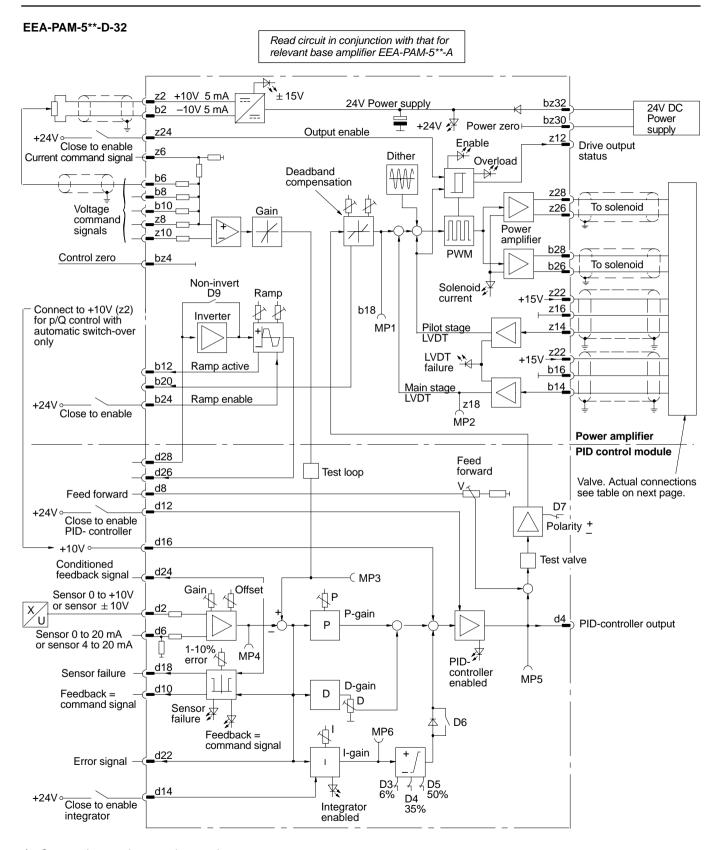


Warning: Electromagnetic Compatibility (EMC)

It is necessary to ensure that the valve is wired up in accordance with the connection arrangements shown in this leaflet. For effective protection, the user's electrical cabinet, the valve subplate or manifold and the cable screens should be connected to efficient earth (ground) points. The metal 7-pin connector part no. 934939 should be used for the integral amplifier.

In all cases, both valve and cable should be kept as far away as possible from any source of electromagnetic radiation such as cables carrying heavy current, relays and certain kinds of portable radio transmitters, etc. Difficult environments could mean that extra screening may be necessary to avoid the interference.

[▲] All amplifiers except EEA-PAM-523/525 models, in which solenoid current is monitored.



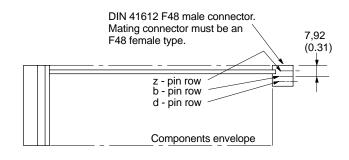
Solenoid and LVDT Connections for Proportional Valves

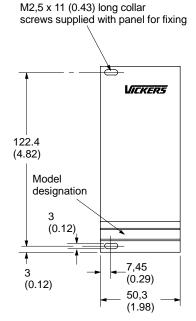
Amplifier type	Solenoid with LVDT and/or for	Solenoid without LVDT, or on pilot	Pilot-stage LVDT, 「, (black plug):				Main-stage LVDT, (gray plug):			
	flow P to B	valve	Pin 1	Pin 2	Pin 3	Pin 4	Pin 1	Pin 2	Pin 3	Pin 4
EEA-PAM-513-D-32	b26/b28	_	_	_	_	Not connected	_	_	_	Not connected
EEA-PAM-523-D-32	b26/b28	z26/z28	_	_	_	Not connected	_	_	_	Not connected
EEA-PAM-525-D-32	b26/b28	z26/z28	_	_	_	Not connected	_	_	_	Not connected
EEA-PAM-533-D-32	b26/b28	z26/z28	_	_	_	Not connected	b14	z22	b16	Not connected
EEA-PAM-535-D-32	b26/b28	z26/z28	_	_	_	Not connected	b14	z22	b16	Not connected
EEA-PAM-541-D-32	_	z26/z28	z14	z22	z16	Not connected	b14	z22	b16	Not connected
EEA-PAM-553-D-32	_	z26/z28	_	_	_	Not connected	b14	z22	b16	Not connected
EEA-PAM-561-D-32	_	z26/z28	_	_	_	Not connected	b14	z22	b16	Not connected
EEA-PAM-568-D-32	_	z26/z28	_	_	_	Not connected	b14	z22	b16	Not connected
EEA-PAM-571-D-32	_	z26/z28	_	_	_	Not connected	b14	z22	b16	Not connected
EEA-PAM-581-D-32	_	z26/z28	z14	z22	z16	Not connected	b14	z22	b16	Not connected

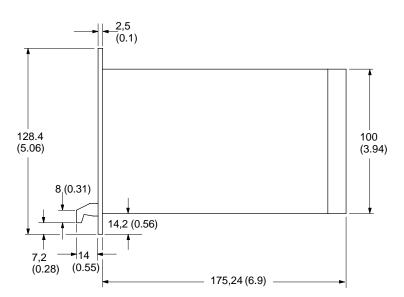
Installation Dimensions in mm (inches)

Plug-in Unit of 3U height, to IEC 297





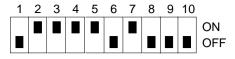




Application Notes

DIL Switches

The controller is configured for the application using DIL switches, located on the board.



Factory setting

The DIL switch operates as follows:

Switch	ON	OFF	
D1:	For sensors with 4 to 20 mA output	For sensors with ±10V or 20 mA outputs	
D2:	P-gain 2 to 50	P-gain 0,1 to 2	
D6:	One-sided limitation of the integrator output. (Only useful for proportional pressure and proportional throttle valves.)	No limitations of integrator output	
D7:	Inverts the controller output signal	Non-inverted signal	
D8:	For sensors with 4 to 20 mA output	For sensors with ± 10 V or 20 mA outputs	
D9:	Ramp signal not inverted	Ramp signal inverted	
D10:	Not used	_	

For p/Q control with automatic switch-over, connect d16 to z2 (+10V). The flow command signal (Q) is applied to the feed-forward input, d8, and the desired pressure setpoint voltage applied to a command signal input (b6/8/10 or z6/8/10). The pressure feedback sensor is connected to the sensor input d2, or d6 as required.

The pressure control loop will override the flow command to limit the pressure to the level determined by the pressure setpoint voltage. Adjust P, I and D gains for best performance.

The switches D3, D4 and D5 belong together. They limit the I output volts between 100% (10V) and 5% (0,5V) as follows:

D3	D4	D5	I-limit
ON	ON	ON	100%
ON	ON	OFF	50%
ON	OFF	ON	35%
ON	OFF	OFF	25%
OFF	ON	ON	5,9%
OFF	ON	OFF	5,8%
OFF	OFF	ON	5,3%
OFF	OFF	OFF	5,0%

Reconfiguration of Controller Parameters

Once the controller parameters have been optimized and set, they can be measured by means of an ohmmeter. This allows easy reconfiguration of the controller on different cards for use as spare parts or on standard machine series.

Four test points are located on the PID-module for this purpose, see diagram for locations. The resistance between the appropriate test point and ground (at the front panel monitor point) determines the controller parameters:

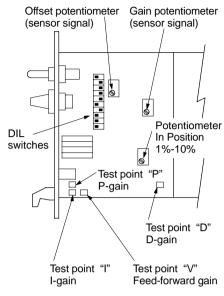
P = P-gain

I = I-gain

D = D-gain

V = Feed-forward gain

Location of User Features on PID Module



Operation of the Integrated Test Mode

The basic operation of the hydraulic actuator can be tested by using the 3-position mode switch mounted on the front panel. To select different modes the toggle switch must be lifted slightly before turning it to a new position.

Caution:

Before setting the mode switch to either "Test valve" or "Test loop" make sure the test potentiometer is set to "0". Otherwise sudden movements of the actuator may occur.

The mode switch has three positions: AUTO

The controller operates in closed-loop mode, using the external command signal. The test potentiometer is disconnected.

TEST VALVE

An open-loop command signal for the valve comes directly from the potentiometer. The external input signal is disconnected. The hydraulic part of the system may be tested in this configuration.

TEST LOOP

The closed-loop command signal for the PID-controller comes directly from the potentiometer. The external signal input is disconnected. This configuration allows for verification of the valve polarity and the control parameters.

